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# IS-900CT Camera Tracker

## PRELIMINARY DATA SHEET

**Creativity is returned to the director.**

For the first time, virtual set and film cameras can be moved and tracked as easily as television cameras. The television and film industries can now utilize the boundary expanding capabilities of computer generated virtual sets and/or special effects and still maintain the creative freedom of camera position they are accustomed to.



- Creative Freedom
- Hand-Held Cameras
- Instant Calibration
- 6 Degrees-of-freedom

The **IS-900CT** camera tracker uses InterSense's revolutionary new CONSTELLATION™ expandable motion tracking technology to provide producers with the ability to make unrestrained use of 6 degree-of-freedom (DOF) camera at a far lower price than sensorized cranes and tripods.

**Instant Calibration.** Unlike older technologies that can take up to half-an-hour to set up and calibrate, InterSense's CONSTELLATION™ technology allows instantaneous calibration. Just push a button and you're ready to go.

**Hand-Held Cameras.** Today's dynamic cinematography techniques demand total camera flexibility. Older technologies required that the camera remain in a fixed position, limiting the range of possibilities. But InterSense gives you complete creative freedom to move the camera or even use hand-held cameras.

**Software Compatibility.** If your CG software supports industry standard trackers, you will be able to use InterSense's camera tracker.

**Technology Overview** The IS-900CT Camera Tracker obtains its primary motion sensor data using a miniature solid-state inertial measurement unit (IMU) which senses angular rate of rotation and linear acceleration along three perpendicular axes. The angular rates are integrated to obtain the orientation (yaw, pitch, and roll) of the sensor, and the linear accelerations are transformed into a reference coordinate frame and double-integrated to keep track of changes in position (x, y, and z).

Ultrasonic time-of-flight distance measurements are used to determine the starting position and to correct any drift in the inertial position.

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